

# Periodic Orbits of Spatial Kepler Problem

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# Background and Collaborators

- Developed result of “The Conley-Zehnder indices of the rotating Kepler problem” by Albers, Fish, Frauenfelder, van Koert, 2013, which deals with planar rotating Kepler problem.
- Based on my ph.D thesis.
- Collaborator: Beomjun Sohn

## 1. **Rotating Kepler Problem**

Three laws of Kepler, invariants, Moser regularization

## 2. **Periodic Orbits of Rotating Kepler Problem**

Classification of periodic orbits, description of moduli space

## 3. **Conley-Zehnder Index of Kepler Orbits**

Computation of CZ index, relation with symplectic homology

# Rotating Kepler Problem

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# Kepler Problem

The **Kepler problem** describes the motion of an object under the gravitational force of a mass at the origin.

Hamiltonian : **Kepler energy**  $E : T^*(\mathbb{R}^3 \setminus \{0\}) \rightarrow \mathbb{R}$ ,

$$E(q, p) = \frac{1}{2}|p|^2 - \frac{1}{|q|}$$

The singularity at 0 will be regularized by Moser regularization.

Planar problem : domain is  $T^*\mathbb{R}^2 \setminus \{0\}$ .

# Three Laws of Kepler

In 17C, Kepler discovered these three laws through observation.

1. The solutions are conic sections with one focus at the origin.  
If  $E < 0$ , every orbit is an **ellipse**.
2. The **areal velocity**  $d\text{Area}/dt = r^2\dot{\theta}/2$  is constant.
3. The period  $\tau$  of solution satisfies  $\tau^2 = -\pi^2/2E^3$ .  
 $\tau$  **only depends on the Kepler energy**.

# Two Invariants

1. **Angular momentum**  $L = q \times p$ .
  - Direction of  $L$  = Normal to the plane which the orbit contained in.
2. **Laplace-Runge-Lenz vector**  $A = p \times L - \frac{q}{|q|}$ 
  - Direction of  $A$  = Direction of the major axis
  - Length of  $A$  = Eccentricity  $\varepsilon$

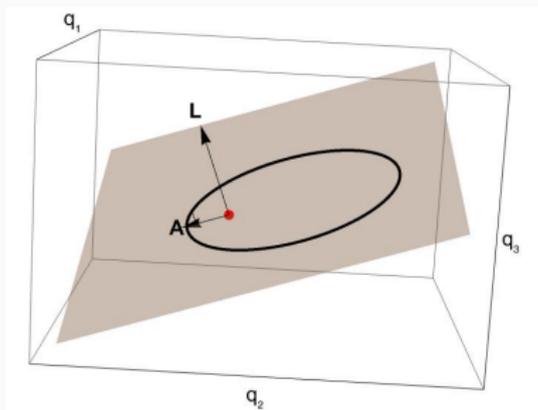
Some relations :

1.  $\{E, L_i\} = \{E, A_j\} = 0$  for any  $i, j$ .
2.  $\{|L|, L_i\} = 0$  for any  $i$ .
3.  $\{L_i, A_j\} = \varepsilon_{ijk} A_k$ . In particular,  $\{L_i, A_i\} = 0$
4.  $\varepsilon^2 = |A|^2 = 2E|L|^2 + 1$ .

## Two Invariants

On  $L \cdot q$ , the Kepler orbit is given in the polar coordinate by

$$r = \frac{|L|^2}{1 + |A| \cos(\theta - g)} \quad (g \text{ is determined by the direction of } A).$$



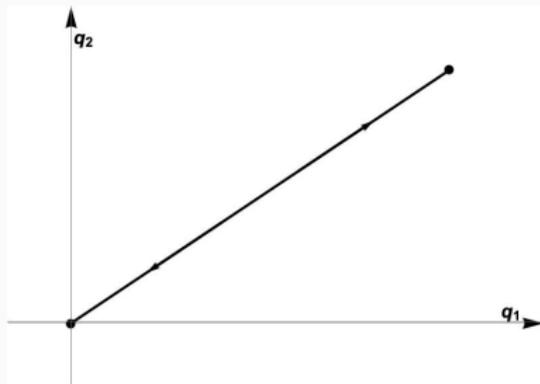
In particular,  $E$ ,  $L$  and  $A$  determine the Kepler orbit.

# Moser Regularization

For  $E_0 < 0$ , we can embed the Hamiltonian flow on the level set  $E^{-1}(E_0)$  into the **unit geodesic flow on  $T^*S^3$** .

$\Rightarrow$  Compactification of the energy level set by  $ST^*S^3 \simeq S^3 \times S^2$ .

The **collision orbits** are added.



This is a special case of ellipse with  $\varepsilon = |A| = 1$ ,  $L = 0$ .

# Rotating Kepler Problem

Kepler problem : Every orbit is periodic  $\Rightarrow$  Too degenerate.

(Real motivation: a limit of the restricted three-body problem)

**Rotating Kepler problem** is defined by Hamiltonian

$$H = E + L_3 = \frac{1}{2}|p|^2 - \frac{1}{|q|} + (q_1 p_2 - q_2 p_1).$$

$H$  : **total energy** or **Jacobi energy** (usually,  $H = c$ )

$E$  : **Kepler energy**.

**Note.** Moser regularization is still valid, gives a Finsler geodesic flow on  $T^*S^3$ , and the energy hypersurface is  $ST^*S^3 \simeq S^3 \times S^2$ .

# Periodic Orbits of Rotating Kepler Problem

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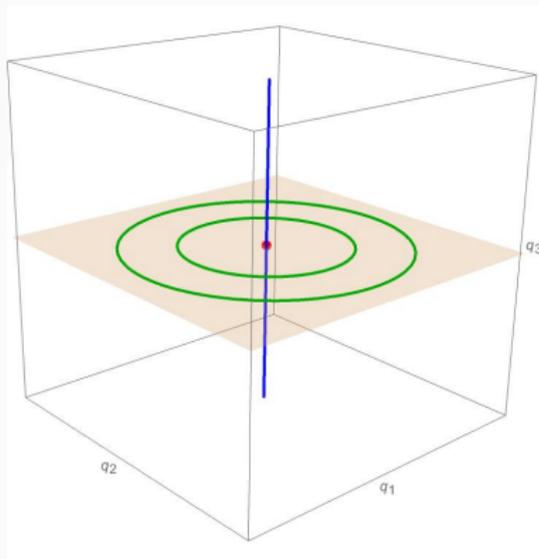
# Periodic Orbits

There are three types of periodic orbits.

1. Two **planar circular orbits**, nondegenerate for generic  $c$ .
2. Two **vertical collision orbits**, nondegenerate for generic  $c$ .
3. Morse-Bott family of degenerate orbits with specific Kepler energy.

**Idea.**  $F\ell^{L_3}$  is a rotation along  $q_3$ - and  $p_3$ -axis, and  $F\ell^H = F\ell^E \circ F\ell^{L_3}$ .

# Nondegenerate Periodic Orbits



**Figure 1:** Planar circular orbits and vertical collision orbits

These are periodic after composing with  $F^L_{L_3}$ .

# Nondegenerate Periodic Orbits

Circular condition:  $\varepsilon^2 = 2EL_3^2 + 1 = 2E(c - E)^2 + 1 = 0$ .

For fixed  $c < -3/2$ , there are 3 **planar circular orbits** with different  $E$ .

1. **Retrograde orbit**  $\gamma_+$ :  $L_3 > 0$ , smaller  $E$  and smaller radius.
2. **Direct orbit**  $\gamma_-$ :  $L_3 < 0$ , larger  $E$  and larger radius.
3. The rest one, outer direct orbit, lies on the unbounded component, and not of our interest (discarded during regularization).

**Vertical collision orbits**  $\gamma_{c\pm}$ :  $L = 0$ ,  $A_3 = \mp 1$ ,  $c = E$ .

- They **do not** appear in the planar problem.

At generic  $c$ , these orbits and their covers are isolated, so nondegenerate.

# Diagram of the Nondegenerate Orbits

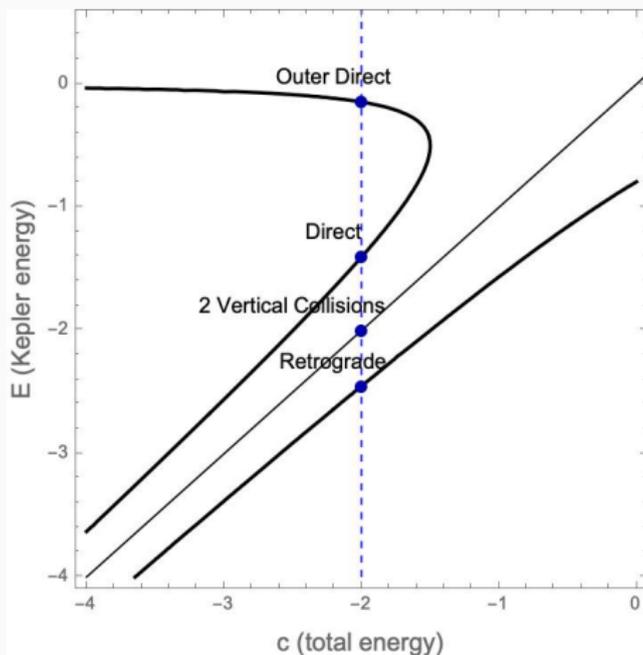


Figure 2: Graph of  $2E(c - E)^2 + 1 = 0$  and the orbits

# Morse-Bott Family

For other cases, the periods of  $E$ -orbit and  $L_3$ -orbit must be the same.

$\tau = 2\pi/(-2E)^{3/2} \Rightarrow$  there exists some  $k, l \in \mathbb{Z}$  such that

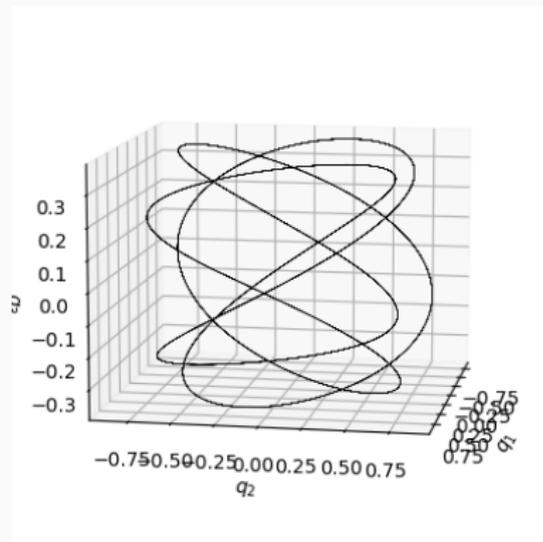
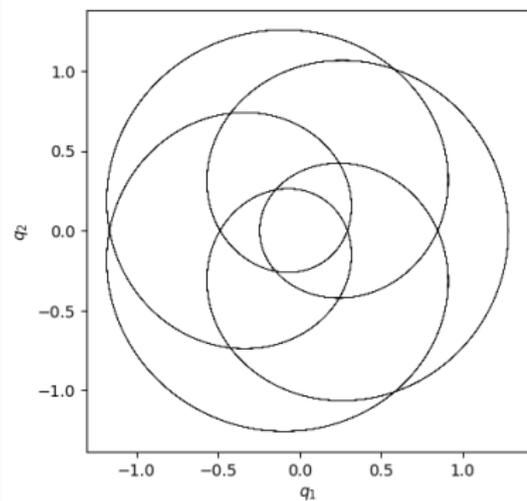
$$k\tau = \frac{2k\pi}{(-2E)^{3/2}} = 2l\pi \Rightarrow E_{k,l} = -\frac{1}{2} \left( \frac{k}{l} \right)^{2/3}$$

For given  $c$ , only orbits with Kepler energy  $E_{k,l}$  can be periodic.

Such orbits appear with Morse-Bott  $S^3$ -family  $\Sigma_{k,l}$ . (will be explained)

**Note.** We have  $S^1$ -families in the planar problem.

# Morse-Bott Family



**Figure 3:** Illustration of periodic orbits on a plane and space <sup>1</sup>

<sup>1</sup>Chankyung Jung drew these nice pictures.

**Recall.**  $E, L$  and  $A$  characterizes the Kepler orbit.

Denote  $x = \sqrt{-2EL} - A$ ,  $y = \sqrt{-2EL} + A$ .

$$\Rightarrow |x|^2 = |y|^2 = -2E|L|^2 + |A|^2 = 1.$$

The moduli space of the Kepler orbits with Kepler energy  $E$  is

$$\mathcal{M}_E = \{(x, y) : |x|^2 = |y|^2 = 1\} \simeq S^2 \times S^2.$$

(Space of unit geodesics of  $S^3$ ) =  $ST^*S^3/S^1 \simeq S^2 \times S^2$ .

**Note.** In the planar problem, the moduli space is  $\mathbb{RP}^3/S^1 \simeq S^2$ .

# Properties of $\mathcal{M}_E$

$L_3 = (x + y)/\sqrt{-2E}$  serves as a Morse function with 4 critical points.

1. The direct orbit  $\gamma_- = (-1, -1)$  has index 0.
2. Vertical collision orbits  $\gamma_{c\pm} = (\pm 1, \mp 1)$  have index 2.
3. The retrograde orbit  $\gamma_+ = (1, 1)$  has index 4.

Every regular level set of  $L_3$  is  $S^3$ .

$\Rightarrow$  Morse-Bott family in the rotating Kepler problem.

(For fixed  $c$ , if  $E = E_{k,l}$ , then  $L_3 = c - E_{k,l}$  is specified.)

# Properties of $\mathcal{M}_E$

$A_3$  also serves as a Morse function.

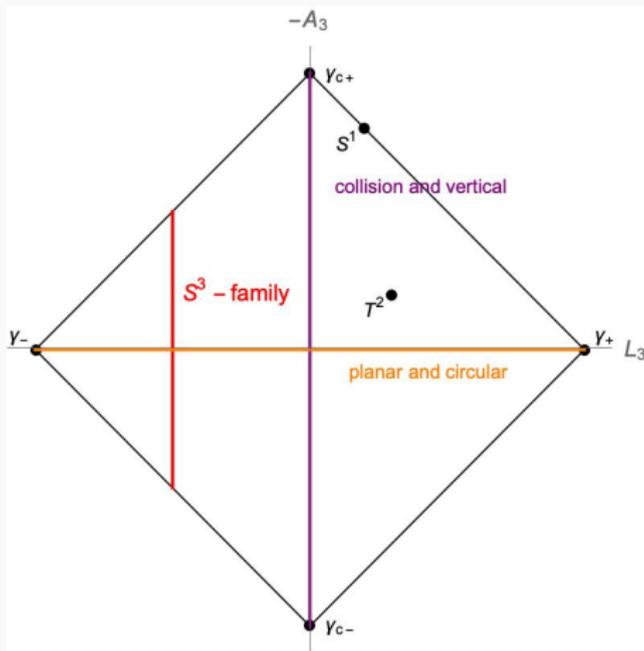
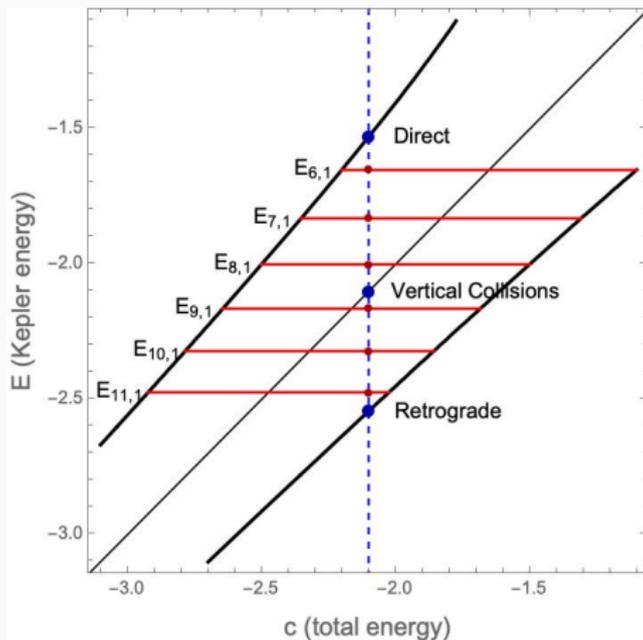


Figure 4: Toric-style diagram of  $\mathcal{M}_E$ .

## Periodic Orbits in $H^{-1}(c)$

For generic energy level  $c$ , the energy hypersurface  $H^{-1}(c)$  contains 4 nondegenerate orbits and (infinitely many) Morse-Bott  $S^3$ -families.



# Conley-Zehnder Indices of Kepler Orbits

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# Conley-Zehnder Index of Planar Circular Orbits

## Theorem

Let  $\gamma_{\pm}$  be the retrograde and direct orbits of Kepler energy  $E$  where  $E \neq E_{k,l}$  for any  $k, l$ . Then  $\gamma_{\pm}$  and their multiple covers are non-degenerate. The Conley-Zehnder index of  $N$ -th iterate of  $\gamma_{\pm}$  is

$$\begin{aligned}\mu_{CZ}(\gamma_{\pm}^N) &= 2 + 4 \max \left\{ n \in \mathbb{Z}_{>0} : n < N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\} \\ &= 2 + 4 \left\lfloor N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\rfloor\end{aligned}$$

The index is exactly the twice compare to the planar problem, which was computed in [AFFvK13].

# Conley-Zehnder Index of Planar Circular Orbits

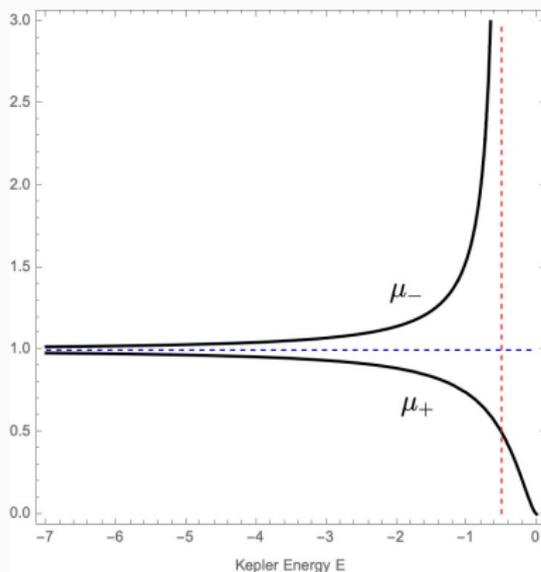


Figure 5: Graph of  $\mu_{\pm} = \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1}$ .

The index of  $\gamma_{+}^N$  **decreases** by 4, while  $\gamma_{-}^N$  **increases** by 4, whenever  $\mu_{\pm}$  touches  $k/N \Leftrightarrow E = E_{N-k,k}$  or  $E = E_{N+k,k}$ . (**bifurcation!**)

# Conley-Zehnder Index of Vertical Collision Orbits

## Theorem

*Let  $\gamma_{c_{\pm}}$  be the vertical collision orbits of Kepler energy  $E$  where  $E \neq E_{k,l}$  for any  $k, l$ . Then  $\gamma_{c_{\pm}}$  and their multiple covers are non-degenerate. The Conley-Zehnder index of  $N$ -th iteration of  $\gamma_{c_{\pm}}$  is*

$$\mu_{CZ}(\gamma_{c_{\pm}}^N) = 4N.$$

*In particular, change of the energy does not change the index.*

# Summary of the Result

Orbits	Initial Index	Index Change
Retrograde $\gamma_+^N$	$4N - 2$ if $E < E_{N-1,1}$	$-4$ at $E = E_{N-k,k}$ for $k = 1, \dots, N - 1$ $= 2$ if $E > E_{1,N-1}$ .
Direct $\gamma_-^N$	$4N + 2$ if $E < E_{N+1,1}$	$+4$ at $E = E_{N+k,k}$ for $k = 1, 2, \dots$
Vertical Collisions $\gamma_{c\pm}^N$	$4N$	No change

**Table 1:** Conley-Zehnder indices of nondegenerate orbits

First bifurcation of  $\gamma_{\pm}^N$  is at  $c = E_{N\mp 1,1} \pm 1/\sqrt{-2E_{N\mp 1,1}}$ .

# Interpretation by Symplectic Homology

$$SH_*^{+,S^1}(T^*S^3) \simeq \begin{cases} \mathbb{Z}_2 & * = 2, \\ \mathbb{Z}_2^2 & * = 2k \geq 4, \\ 0 & \text{otherwise.} \end{cases}$$

For fixed  $N$ , there exists  $c \ll -3/2$  such that  $H^{-1}(c)$  consists of

1.  $k(\leq N)$ -th covers of  $\gamma_{\pm}$  of index  $4k \mp 2$ . (No bifurcation)
2. Higher covers have index  $> 4N + 2$ .

Up to degree  $4N + 2$ , we have

1. One generator at degree 2. ( $\gamma_{+}$ .)
2. Two generators at degree 6, 10, 14,  $\dots$ ,  $4N + 2$ . ( $\gamma_{+}^{k+1}$  and  $\gamma_{-}^k$ .)
3. Two generators at degree 4, 8, 12,  $\dots$ ,  $4N$ . ( $\gamma_{c+}^k$  and  $\gamma_{c-}^k$ .)

This describes  $SH_*^{+,S^1}(T^*S^3)$  up to degree  $4N + 2$  completely.

# Morse-Bott Spectral Sequence

**Case** : Reeb orbits with the same period  $\tau$  form a submanifold  $\Sigma$  which satisfies **Morse-Bott condition** :  $\det(dFl_{\tau}^{X_H}|_{\nu\Sigma} - \text{Id}|_{\nu\Sigma}) \neq 0$ .

## Theorem

*There exists a spectral sequence converging to  $SH^{+,S^1}(W)$  whose  $E^1$ -page is given by*

$$E_{pq}^1(SH^{S^1,+}) = \begin{cases} \bigoplus_{\Sigma \in C(p)} H_{p+q-\text{shift}(\Sigma)}^{S^1}(\Sigma) & p > 0 \\ 0 & p \leq 0 \end{cases}$$

*where  $\text{shift}(\Sigma) = \mu_{RS}(\Sigma) - \frac{1}{2} \dim \Sigma / S^1$ .*

# Morse-Bott Property

We compute the linearized return map by using **action-angle coordinates**.

In the planar problem, [AFFvK13] used **Delaunay coordinate** given by  $(p_l, p_g) = (1/\sqrt{-2E}, L_3)$ , which degenerate at planar circular orbits.

In the spatial problem, we should use two coordinates:

1. Delaunay coordinate :  $(p_l, p_g, p_\theta) = (1/\sqrt{-2E}, |L|, L_3)$ .

But this coordinate system degenerates at every planar orbit.

2. **LRL coordinate** :  $(p_l, p_\eta, p_\theta) = (1/\sqrt{-2E}, A_3, L_3)$ .

This degenerates at every circular orbit, but covers planar orbits.

# Conley-Zehnder Index of Degenerate Orbits

As we increase the Kepler energy level  $E$  from  $E_{k,l} - \varepsilon$  to  $E_{k,l} + \varepsilon$ ,

1. **Retrograde:**  $\mu_{CZ}(\gamma_+^{k+l})$  decreases from  $4k + 2$  to  $4k - 2$ .
2. **Direct:**  $\mu_{CZ}(\gamma_-^{k-l})$  increases from  $4k - 2$  to  $4k + 2$ .
3. **Morse-Bott family:** At  $E = E_{k,l}$ ,  $S^3$ -family  $\Sigma_{k,l}$  emerges.

## Theorem

*Index of  $S^3$ -family  $\Sigma_{k,l}$  with Kepler energy  $E_{k,l}$  is*

$$\begin{aligned}\mu_{CZ}(\Sigma_{k,l}) &= \text{shift}(\Sigma) + \dim S^3/2 \\ &= (4k - 2) + 3/2 = 4k - 1/2.\end{aligned}$$

# Conley-Zehnder Index of Degenerate Orbits

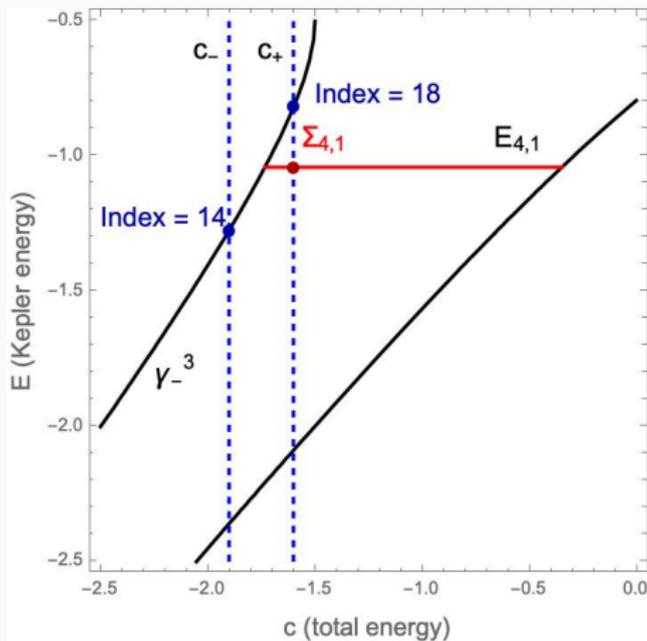
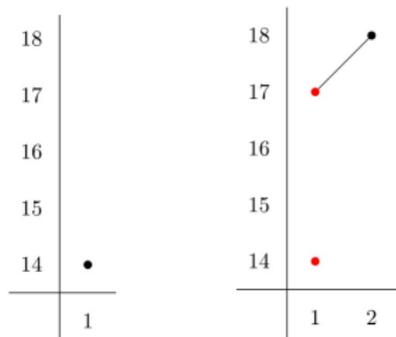


Figure 6: Bifurcation diagram of  $\gamma_-^3$  at  $E = E_{4,1}$

# Morse-Bott Spectral Sequence

(Local) Morse-Bott spectral sequence of  $SH^{S^1,+}$



Left:  $H = c_-$ , triple cover of direct orbit with index 14.

Right:  $H = c_+$ , triple cover of direct orbit with index 18,

$\Rightarrow S^3$ -family must have shift 14, so  $\mu_{CZ}(\Sigma_{4,1}) = 14 + 3/2 = 15.5$ .

Questions / Comments / Suggestions

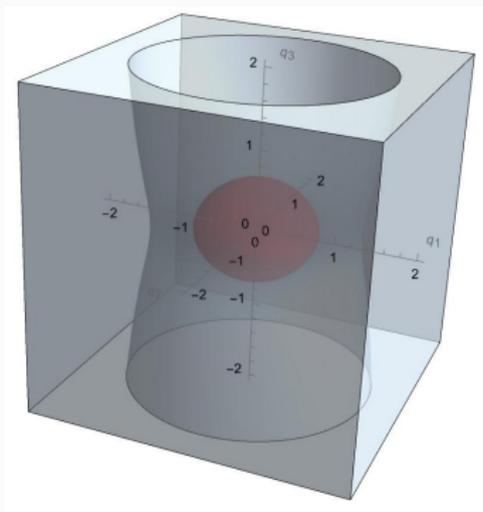


## Appendix 1. Hill's Region

$$H(q, p) = \underbrace{\frac{1}{2} \left( (p_1 - q_2)^2 + (p_2 + q_1)^2 \right)}_{\text{nonnegative}} + \underbrace{\left( -\frac{1}{|q|} - \frac{q_1^2 + q_2^2}{2} \right)}_{\text{effective potential } U(q)}$$

$H = c \Rightarrow U(q) \leq c$ , and  $\{q : U(q) \leq c\}$  is called a **Hill's region**.

If  $c < -3/2$ , the Hill's region has a bounded component (red ball).



## Appendix 2. Moser Regularization

Fix  $E = E_0$ . Consider the Hamiltonian on  $T^*\mathbb{R}^3$

$$\tilde{K}(q, p) = \frac{1}{2} (|q| (E(q, p) - E_0) + 1)^2 = \frac{1}{2} \left( \frac{1}{2} (|p|^2 - 2E_0) |q| \right)^2.$$

This is the Hamiltonian of geodesic vector field on  $T^*S_r^3$  under the stereographic projection

$$\begin{aligned} \Phi_r : T^*S_r^3 &\rightarrow T^*\mathbb{R}^3 \\ (x, y) &\mapsto \left( \frac{r\vec{x}}{r-x_0}, \frac{r-x_0}{r}\vec{y} + \frac{y_0}{r}\vec{x} \right) \end{aligned}$$

where  $r = \sqrt{-2E_0}$ , composed with a switch map  $(q, p) \mapsto (-p, q)$ .

## Appendix 2. Moser Regularization

On  $T_r^*S^3$ , we have

$$K_r = \frac{r^4}{2}|y|^2$$

The level set  $E^{-1}(E_0)$  can be embedded into  $K^{-1}(1/2)$

$\Rightarrow$  Kepler Hamiltonian vector field and geodesic vector field are parallel.

$$X_K|_{E^{-1}(E_0)}(p, q) = |q|X_E|_{E^{-1}(E_0)}(-q, p).$$

We regard Kepler problem as a **sub-system of the geodesic flow on  $T^*S^3$** .

## Appendix 3. Restricted Circular Three-body Problem

**Restricted circular three-body problem** describes a motion of a massless body under the gravitational force of two objects with mass ratio  $\mu$ , and assume the motions of two bodies are **circular**.

Corresponding Hamiltonian is time-dependent.

$$E_t(q, p) = \frac{1}{2}|p|^2 - \frac{\mu}{|q - m(t)|} - \frac{1 - \mu}{|q - e(t)|},$$
$$e(t) = -\mu(\cos t, -\sin t, 0), \quad m(t) = (1 - \mu)(\cos t, -\sin t, 0)$$

In rotating frame, the Hamiltonian is **autonomous** (time-independent).

$$H = \frac{1}{2}|p|^2 - \frac{\mu}{|q - (1 - \mu)|} - \frac{1 - \mu}{|q - \mu|} + (q_1 p_2 - q_2 p_1)$$

Rotating Kepler problem is a limit case,  $\mu = 0$ .

## Appendix 3. Restricted Circular Three-body Problem

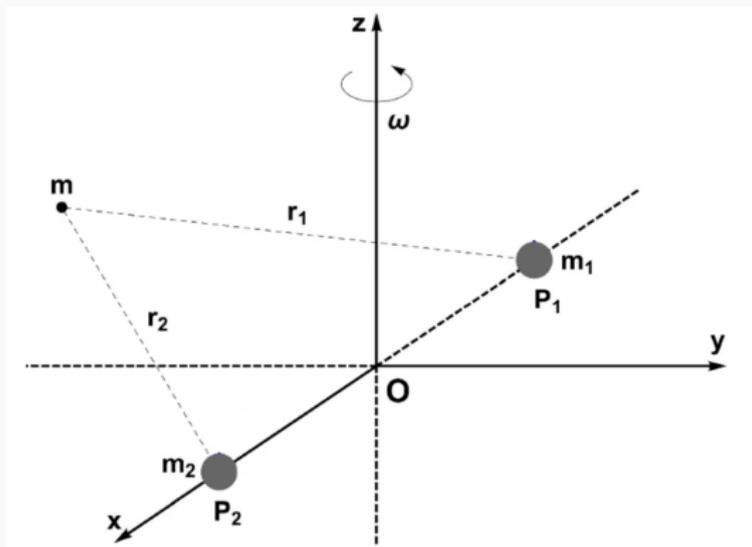


Figure 7: Restricted circular three-body problem<sup>2</sup>

<sup>2</sup>H. Alrebdi, F.Dubeibe, K.Papadakis, E.Zotos “Equilibrium dynamics of a circular restricted three-body problem with Kerr-like primaries”

## Appendix 4. How to compute the CZ index?

1. For nondegenerate orbits, find a parametrization and period.
2. Find symplectic frame which can be extended to the capping disk.
  - For planar circular orbits, an appropriate global frame in  $T^*\mathbb{R}^2$  was introduced in [AFFvK13]. We extended the frame to  $T^*\mathbb{R}^3$ .
  - For vertical collision orbits, we used other frame.
3. Compute the linearized flow and crossing forms.
  - For vertical collision orbits, we splitted the flow into  $E$ -part and  $L_3$ -part. For the singularity of  $E$ -part, we used a limit argument.
4. Use Morse-Bott spectral sequence to compute the index of degenerate orbits.

## Appendix 5. Result in the Planar Problem

### Theorem (AFFvK13)

Let  $\gamma_{\pm}$  be the retrograde and direct orbits of Kepler energy  $E$  where  $E \neq E_{k,l}$  for any  $k, l$ . Then  $\gamma_{\pm}$  and their multiple covers are non-degenerate. The Conley-Zehnder index of  $N$ -th iterate of  $\gamma_{\pm}$  is

$$\begin{aligned}\mu_{CZ}(\gamma_{\pm}^N) &= 1 + 2 \max \left\{ n \in \mathbb{Z}_{>0} : n < N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\} \\ &= 1 + 2 \left\lfloor N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\rfloor\end{aligned}$$

This shows the dynamical convexity of the planar rotating Kepler problem. (The energy hypersurface is  $\mathbb{R}P^3$ , and the retrograde orbit is non-contractible but its double cover is.)

Thank you for your attention!

