

Periodic Orbits of Spatial Kepler Problem

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Background and Collaborators

- Developed result of “The Conley-Zehnder indices of the rotating Kepler problem” by Albers, Fish, Frauenfelder, van Koert, 2013, which deals with planar rotating Kepler problem.
- Based on my ph.D thesis.
- Collaborator: Beomjun Sohn

1. **Rotating Kepler Problem**

Three laws of Kepler, invariants, Moser regularization

2. **Periodic Orbits of Rotating Kepler Problem**

Classification of periodic orbits, description of moduli space

3. **Conley-Zehnder Index of Kepler Orbits**

Computation of CZ index, relation with symplectic homology

Rotating Kepler Problem

Kepler Problem

The **Kepler problem** describes the motion of an object under the gravitational force of a mass at the origin.

Hamiltonian : **Kepler energy** $E : T^*(\mathbb{R}^3 \setminus \{0\}) \rightarrow \mathbb{R}$,

$$E(q, p) = \frac{1}{2}|p|^2 - \frac{1}{|q|}$$

The singularity at 0 will be regularized by Moser regularization.

Planar problem : domain is $T^*\mathbb{R}^2 \setminus \{0\}$.

Three Laws of Kepler

In 17C, Kepler discovered these three laws through observation.

1. The solutions are conic sections with one focus at the origin.
If $E < 0$, every orbit is an **ellipse**.
2. The **areal velocity** $d\text{Area}/dt = r^2\dot{\theta}/2$ is constant.
3. The period τ of solution satisfies $\tau^2 = -\pi^2/2E^3$.
 τ **only depends on the Kepler energy**.

Two Invariants

1. **Angular momentum** $L = q \times p$.
 - Direction of L = Normal to the plane which the orbit contained in.
2. **Laplace-Runge-Lenz vector** $A = p \times L - \frac{q}{|q|}$
 - Direction of A = Direction of the major axis
 - Length of A = Eccentricity ε

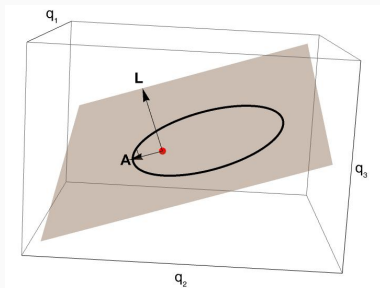
Some relations :

1. $\{E, L_i\} = \{E, A_j\} = 0$ for any i, j .
2. $\{|L|, L_i\} = 0$ for any i .
3. $\{L_i, A_j\} = \varepsilon_{ijk} A_k$. In particular, $\{L_i, A_i\} = 0$
4. $\varepsilon^2 = |A|^2 = 2E|L|^2 + 1$.

Two Invariants

On $L \cdot q$, the Kepler orbit is given in the polar coordinate by

$$r = \frac{|L|^2}{1 + |A| \cos(\theta - g)} \quad (g \text{ is determined by the direction of } A).$$



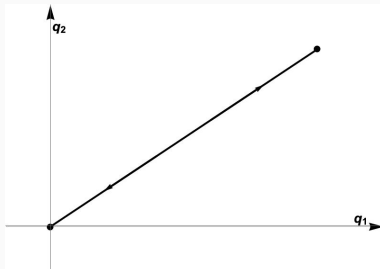
In particular, E , L and A determine the Kepler orbit.

Moser Regularization

For $E_0 < 0$, we can embed the Hamiltonian flow on the level set $E^{-1}(E_0)$ into the **unit geodesic flow on T^*S^3** .

\Rightarrow Compactification of the energy level set by $ST^*S^3 \simeq S^3 \times S^2$.

The **collision orbits** are added.



This is a special case of ellipse with $\varepsilon = |A| = 1$, $L = 0$.

Rotating Kepler Problem

Kepler problem : Every orbit is periodic \Rightarrow Too degenerate.

(Real motivation: a limit of the restricted three-body problem)

Rotating Kepler problem is defined by Hamiltonian

$$H = E + L_3 = \frac{1}{2}|p|^2 - \frac{1}{|q|} + (q_1 p_2 - q_2 p_1).$$

H : **total energy** or **Jacobi energy** (usually, $H = c$)

E : **Kepler energy**.

Note. Moser regularization is still valid, gives a Finsler geodesic flow on T^*S^3 , and the energy hypersurface is $ST^*S^3 \simeq S^3 \times S^2$.

Periodic Orbits of Rotating Kepler Problem

Periodic Orbits

There are three types of periodic orbits.

1. Two **planar circular orbits**, nondegenerate for generic c .
2. Two **vertical collision orbits**, nondegenerate for generic c .
3. Morse-Bott family of degenerate orbits with specific Kepler energy.

Idea. Fl^{L_3} is a rotation along q_3 - and p_3 -axis, and $Fl^H = Fl^E \circ Fl^{L_3}$.

Nondegenerate Periodic Orbits

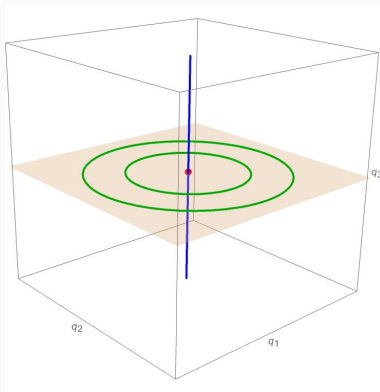


Figure 1: Planar circular orbits and vertical collision orbits

These are periodic after composing with $F\iota^{L_3}$.

Nondegenerate Periodic Orbits

Circular condition: $\varepsilon^2 = 2EL_3^2 + 1 = 2E(c - E)^2 + 1 = 0$.

For fixed $c < -3/2$, there are 3 **planar circular orbits** with different E .

1. **Retrograde orbit** γ_+ : $L_3 > 0$, smaller E and smaller radius.
2. **Direct orbit** γ_- : $L_3 < 0$, larger E and larger radius.
3. The rest one, outer direct orbit, lies on the unbounded component, and not of our interest (discarded during regularization).

Vertical collision orbits $\gamma_{c\pm}$: $L = 0$, $A_3 = \mp 1$, $c = E$.

- They **do not** appear in the planar problem.

At generic c , these orbits and their covers are isolated, so nondegenerate.

Diagram of the Nondegenerate Orbits

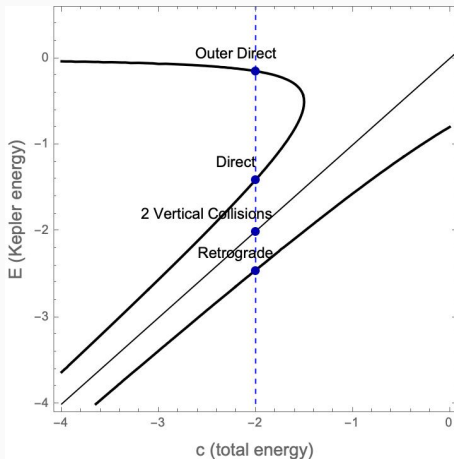


Figure 2: Graph of $2E(c - E)^2 + 1 = 0$ and the orbits

Morse-Bott Family

For other cases, the periods of E -orbit and L_3 -orbit must be the same.

$\tau = 2\pi/(-2E)^{3/2} \Rightarrow$ there exists some $k, l \in \mathbb{Z}$ such that

$$k\tau = \frac{2k\pi}{(-2E)^{3/2}} = 2l\pi \Rightarrow E_{k,l} = -\frac{1}{2} \left(\frac{k}{l} \right)^{2/3}$$

For given c , only orbits with Kepler energy $E_{k,l}$ can be periodic.

Such orbits appear with Morse-Bott S^3 -family $\Sigma_{k,l}$. (will be explained)

Note. We have S^1 -families in the planar problem.

Morse-Bott Family

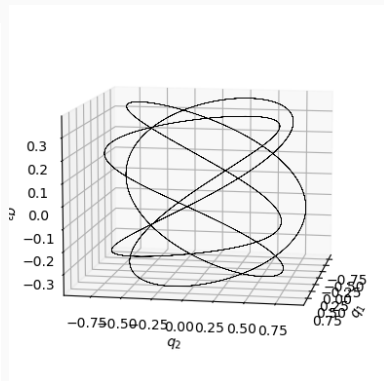
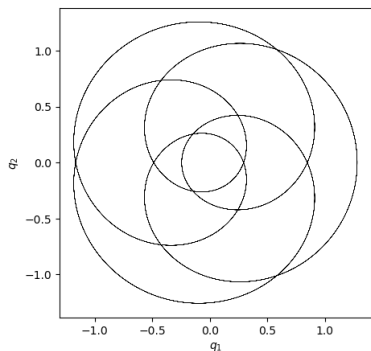


Figure 3: Illustration of periodic orbits on a plane and space ¹

¹Chankyu Joung drew these nice pictures.

Recall. E, L and A characterizes the Kepler orbit.

Denote $x = \sqrt{-2EL} - A$, $y = \sqrt{-2EL} + A$.

$$\Rightarrow |x|^2 = |y|^2 = -2E|L|^2 + |A|^2 = 1.$$

The moduli space of the Kepler orbits with Kepler energy E is

$$\mathcal{M}_E = \{(x, y) : |x|^2 = |y|^2 = 1\} \simeq S^2 \times S^2.$$

(Space of unit geodesics of S^3) = $ST^*S^3/S^1 \simeq S^2 \times S^2$.

Note. In the planar problem, the moduli space is $\mathbb{RP}^3/S^1 \simeq S^2$.

Properties of \mathcal{M}_E

$L_3 = (x + y)/\sqrt{-2E}$ serves as a Morse function with 4 critical points.

1. The direct orbit $\gamma_- = (-1, -1)$ has index 0.
2. Vertical collision orbits $\gamma_{c\pm} = (\pm 1, \mp 1)$ have index 2.
3. The retrograde orbit $\gamma_+ = (1, 1)$ has index 4.

Every regular level set of L_3 is S^3 .

\Rightarrow Morse-Bott family in the rotating Kepler problem.

(For fixed c , if $E = E_{k,l}$, then $L_3 = c - E_{k,l}$ is specified.)

Properties of \mathcal{M}_E

A_3 also serves as a Morse function.

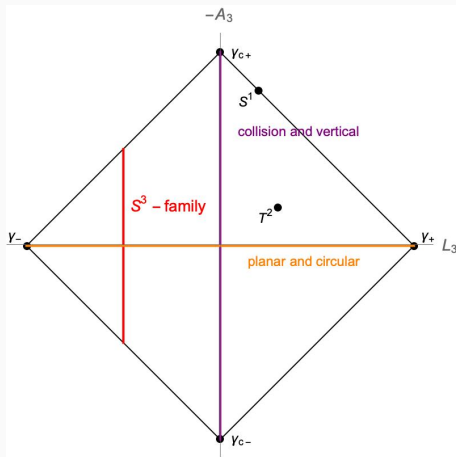
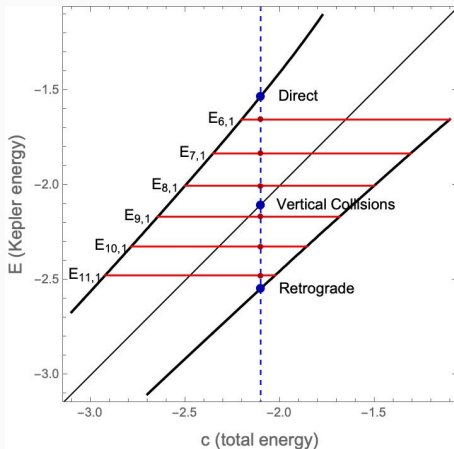


Figure 4: Toric-style diagram of \mathcal{M}_E .

Periodic Orbits in $H^{-1}(c)$

For generic energy level c , the energy hypersurface $H^{-1}(c)$ contains 4 nondegenerate orbits and (infinitely many) Morse-Bott S^3 -families.



Conley-Zehnder Indices of Kepler Orbits

Conley-Zehnder Index of Planar Circular Orbits

Theorem

Let γ_{\pm} be the retrograde and direct orbits of Kepler energy E where $E \neq E_{k,l}$ for any k, l . Then γ_{\pm} and their multiple covers are non-degenerate. The Conley-Zehnder index of N -th iterate of γ_{\pm} is

$$\begin{aligned}\mu_{CZ}(\gamma_{\pm}^N) &= 2 + 4 \max \left\{ n \in \mathbb{Z}_{>0} : n < N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\} \\ &= 2 + 4 \left\lfloor N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\rfloor\end{aligned}$$

The index is exactly the twice compare to the planar problem, which was computed in [AFFvK13].

Conley-Zehnder Index of Planar Circular Orbits

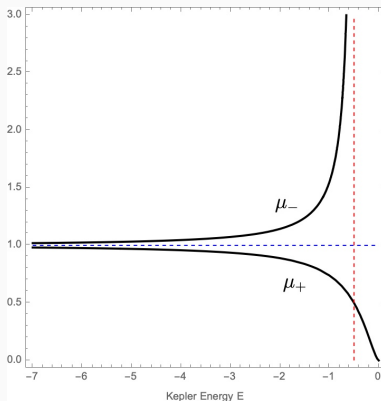


Figure 5: Graph of $\mu_{\pm} = \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1}$.

The index of γ_+^N decreases by 4, while γ_-^N increases by 4, whenever μ_{\pm} touches $k/N \Leftrightarrow E = E_{N-k,k}$ or $E = E_{N+k,k}$. (bifurcation!)

Conley-Zehnder Index of Vertical Collision Orbits

Theorem

Let $\gamma_{c\pm}$ be the vertical collision orbits of Kepler energy E where $E \neq E_{k,l}$ for any k, l . Then $\gamma_{c\pm}$ and their multiple covers are non-degenerate. The Conley-Zehnder index of N -th iteration of $\gamma_{c\pm}$ is

$$\mu_{CZ}(\gamma_{c\pm}^N) = 4N.$$

In particular, change of the energy does not change the index.

Summary of the Result

Orbits	Initial Index	Index Change
Retrograde γ_+^N	$4N - 2$ if $E < E_{N-1,1}$	-4 at $E = E_{N-k,k}$ for $k = 1, \dots, N - 1$ $= 2$ if $E > E_{1,N-1}$.
Direct γ_-^N	$4N + 2$ if $E < E_{N+1,1}$	$+4$ at $E = E_{N+k,k}$ for $k = 1, 2, \dots$
Vertical Collisions $\gamma_{c\pm}^N$	$4N$	No change

Table 1: Conley-Zehnder indices of nondegenerate orbits

First bifurcation of γ_{\pm}^N is at $c = E_{N\mp 1,1} \pm 1/\sqrt{-2E_{N\mp 1,1}}$.

Interpretation by Symplectic Homology

$$SH_*^{+,S^1}(T^*S^3) \simeq \begin{cases} \mathbb{Z}_2 & * = 2, \\ \mathbb{Z}_2^2 & * = 2k \geq 4, \\ 0 & \text{otherwise.} \end{cases}$$

For fixed N , there exists $c \ll -3/2$ such that $H^{-1}(c)$ consists of

1. $k(\leq N)$ -th covers of γ_{\pm} of index $4k \mp 2$. (No bifurcation)
2. Higher covers have index $> 4N + 2$.

Up to degree $4N + 2$, we have

1. One generator at degree 2. (γ_{+} .)
2. Two generators at degree 6, 10, 14, \dots , $4N + 2$. (γ_{+}^{k+1} and γ_{-}^k .)
3. Two generators at degree 4, 8, 12, \dots , $4N$. (γ_{c+}^k and γ_{c-}^k .)

This describes $SH_*^{+,S^1}(T^*S^3)$ up to degree $4N + 2$ completely.

Morse-Bott Spectral Sequence

Case : Reeb orbits with the same period τ form a submanifold Σ which satisfies **Morse-Bott condition** : $\det(dFl_{\tau}^{X_H}|_{\nu\Sigma} - \text{Id}|_{\nu\Sigma}) \neq 0$.

Theorem

There exists a spectral sequence converging to $SH^{+,S^1}(W)$ whose E^1 -page is given by

$$E_{pq}^1(SH^{S^1,+}) = \begin{cases} \bigoplus_{\Sigma \in C(p)} H_{p+q-\text{shift}(\Sigma)}^{S^1}(\Sigma) & p > 0 \\ 0 & p \leq 0 \end{cases}$$

where $\text{shift}(\Sigma) = \mu_{RS}(\Sigma) - \frac{1}{2} \dim \Sigma / S^1$.

Morse-Bott Property

We compute the linearized return map by using **action-angle coordinates**.

In the planar problem, [AFFvK13] used **Delaunay coordinate** given by $(p_l, p_g) = (1/\sqrt{-2E}, L_3)$, which degenerate at planar circular orbits.

In the spatial problem, we should use two coordinates:

1. Delaunay coordinate : $(p_l, p_g, p_\theta) = (1/\sqrt{-2E}, |L|, L_3)$.

But this coordinate system degenerates at every planar orbit.

2. **LRL coordinate** : $(p_l, p_\eta, p_\theta) = (1/\sqrt{-2E}, A_3, L_3)$.

This degenerates at every circular orbit, but covers planar orbits.

Conley-Zehnder Index of Degenerate Orbits

As we increase the Kepler energy level E from $E_{k,l} - \varepsilon$ to $E_{k,l} + \varepsilon$,

1. **Retrograde:** $\mu_{CZ}(\gamma_+^{k+l})$ decreases from $4k + 2$ to $4k - 2$.
2. **Direct:** $\mu_{CZ}(\gamma_-^{k-l})$ increases from $4k - 2$ to $4k + 2$.
3. **Morse-Bott family:** At $E = E_{k,l}$, S^3 -family $\Sigma_{k,l}$ emerges.

Theorem

Index of S^3 -family $\Sigma_{k,l}$ with Kepler energy $E_{k,l}$ is

$$\begin{aligned}\mu_{CZ}(\Sigma_{k,l}) &= \text{shift}(\Sigma) + \dim S^3/2 \\ &= (4k - 2) + 3/2 = 4k - 1/2.\end{aligned}$$

Conley-Zehnder Index of Degenerate Orbits

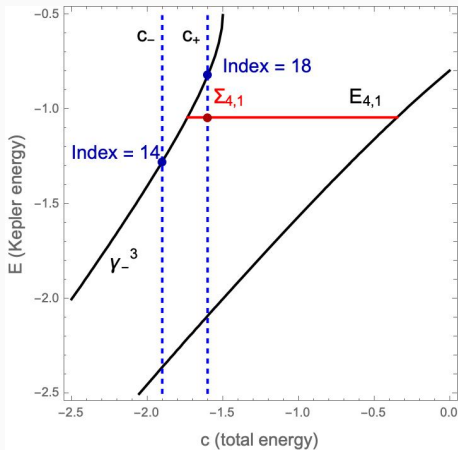
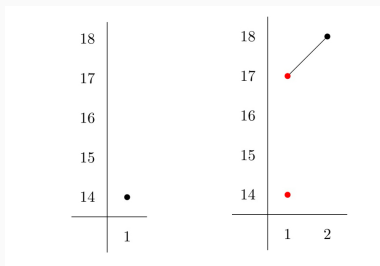


Figure 6: Bifurcation diagram of γ_-^3 at $E = E_{4,1}$

Morse-Bott Spectral Sequence

(Local) Morse-Bott spectral sequence of $SH^{S^1,+}$



Left: $H = c_-$, triple cover of direct orbit with index 14.

Right: $H = c_+$, triple cover of direct orbit with index 18,

$\Rightarrow S^3$ -family must have shift 14, so $\mu_{CZ}(\Sigma_{4,1}) = 14 + 3/2 = 15.5$.

Questions / Comments / Suggestions

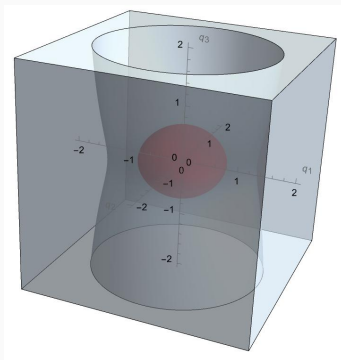


Appendix 1. Hill's Region

$$H(q, p) = \underbrace{\frac{1}{2} ((p_1 - q_2)^2 + (p_2 + q_1)^2)}_{\text{nonnegative}} + \underbrace{\left(-\frac{1}{|q|} - \frac{q_1^2 + q_2^2}{2} \right)}_{\text{effective potential } U(q)}$$

$H = c \Rightarrow U(q) \leq c$, and $\{q : U(q) \leq c\}$ is called a **Hill's region**.

If $c < -3/2$, the Hill's region has a bounded component (red ball).



Appendix 2. Moser Regularization

Fix $E = E_0$. Consider the Hamiltonian on $T^*\mathbb{R}^3$

$$\tilde{K}(q, p) = \frac{1}{2} (|q| (E(q, p) - E_0) + 1)^2 = \frac{1}{2} \left(\frac{1}{2} (|p|^2 - 2E_0) |q| \right)^2.$$

This is the Hamiltonian of geodesic vector field on $T^*S_r^3$ under the stereographic projection

$$\begin{aligned} \Phi_r : T^*S_r^3 &\rightarrow T^*\mathbb{R}^3 \\ (x, y) &\mapsto \left(\frac{r\vec{x}}{r - x_0}, \frac{r - x_0}{r} \vec{y} + \frac{y_0}{r} \vec{x} \right) \end{aligned}$$

where $r = \sqrt{-2E_0}$, composed with a switch map $(q, p) \mapsto (-p, q)$.

Appendix 2. Moser Regularization

On $T_r^*S^3$, we have

$$K_r = \frac{r^4}{2}|y|^2$$

The level set $E^{-1}(E_0)$ can be embedded into $K^{-1}(1/2)$

\Rightarrow Kepler Hamiltonian vector field and geodesic vector field are parallel.

$$X_K|_{E^{-1}(E_0)}(p, q) = |q|X_E|_{E^{-1}(E_0)}(-q, p).$$

We regard Kepler problem as a **sub-system of the geodesic flow on T^*S^3** .

Appendix 3. Restricted Circular Three-body Problem

Restricted circular three-body problem describes a motion of a massless body under the gravitational force of two objects with mass ratio μ , and assume the motions of two bodies are **circular**.

Corresponding Hamiltonian is time-dependent.

$$E_t(q, p) = \frac{1}{2}|p|^2 - \frac{\mu}{|q - m(t)|} - \frac{1 - \mu}{|q - e(t)|},$$
$$e(t) = -\mu(\cos t, -\sin t, 0), \quad m(t) = (1 - \mu)(\cos t, -\sin t, 0)$$

In rotating frame, the Hamiltonian is **autonomous** (time-independent).

$$H = \frac{1}{2}|p|^2 - \frac{\mu}{|q - (1 - \mu)|} - \frac{1 - \mu}{|q - \mu|} + (q_1 p_2 - q_2 p_1)$$

Rotating Kepler problem is a limit case, $\mu = 0$.

Appendix 3. Restricted Circular Three-body Problem

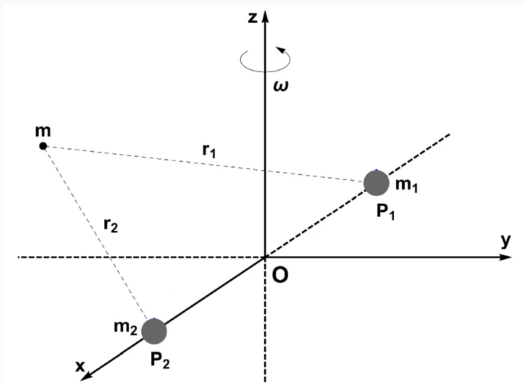


Figure 7: Restricted circular three-body problem²

²H. Alrebdi, F.Dubeibe, K.Papadakis, E.Zotos “Equilibrium dynamics of a circular restricted three-body problem with Kerr-like primaries”

Appendix 4. How to compute the CZ index?

1. For nondegenerate orbits, find a parametrization and period.
2. Find symplectic frame which can be extended to the capping disk.
 - For planar circular orbits, an appropriate global frame in $T^*\mathbb{R}^2$ was introduced in [AFFvK13]. We extended the frame to $T^*\mathbb{R}^3$.
 - For vertical collision orbits, we used other frame.
3. Compute the linearized flow and crossing forms.
 - For vertical collision orbits, we splitted the flow into E -part and L_3 -part. For the singularity of E -part, we used a limit argument.
4. Use Morse-Bott spectral sequence to compute the index of degenerate orbits.

Appendix 5. Result in the Planar Problem

Theorem (AFFvK13)

Let γ_{\pm} be the retrograde and direct orbits of Kepler energy E where $E \neq E_{k,l}$ for any k, l . Then γ_{\pm} and their multiple covers are non-degenerate. The Conley-Zehnder index of N -th iterate of γ_{\pm} is

$$\begin{aligned}\mu_{CZ}(\gamma_{\pm}^N) &= 1 + 2 \max \left\{ n \in \mathbb{Z}_{>0} : n < N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\} \\ &= 1 + 2 \left\lfloor N \frac{(-2E)^{3/2}}{(-2E)^{3/2} \pm 1} \right\rfloor\end{aligned}$$

This shows the dynamical convexity of the planar rotating Kepler problem. (The energy hypersurface is \mathbb{RP}^3 , and the retrograde orbit is non-contractible but its double cover is.)

Thank you for your attention!

